

A STOCHASTIC DIFFUSION MODEL BASED ON THE GAMMA DENSITY FUNCTION: STATISTICAL INFERENCE

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Abstract.

In this paper we propose a new stochastic diffusion process based on the Gamma density function (the trend of this process is proportional to the Gamma density function). Such a process can be considered as an extension of the lognormal diffusion process. From the corresponding Ito's stochastic differential equation and the Kolmogorov equations, we obtain the analytical expression of this process, its transition probability function and its trend function. We then study the statistical inference on it. Based on discrete sampling, we obtain the likelihood estimators of the parameter distribution and the confidence interval of the parameters. Finally, an application on simulated data is considered.

Keywords: Gamma diffusion process, Trend function, Statistical inference in diffusion process, Discrete sampling, Simulation.

AMS classification: 60J60, 62M05

§1. Introduction

Diffusion processes, which play a fundamental role in stochastic modelling, are studied either from the standpoint of the corresponding Ito stochastic differential equations or from that of the associated Kolmogorov (Fokker-Planck and backward) partial differential equations. This role can be seen in applications in fields such as biology, physics, demography, economics, finance and environmental sciences.

Questions of statistical inference and parameter estimation in these processes have received considerable attention in recent years, both when the process is observed continuously and when discretely. In most cases, parameter estimation is based on approximating the maximum likelihood (ML) methodology. A large body of literature addresses this question, and important studies in general or in particular cases include Bibby and Sorensen [4]; Durham and Gallant [6], Eugene [8] and the extensive review given in Prakasa-Rao [16] and Kutoyants [15], without overlooking the early works focused on other methodologies, such as the generalized method of moments by Chan et al. [5], the non parametric method of Arapis and Gao [2], and a method based on Bayesian analysis by Elerian et al. [7].

Diffusion processes, with their associated statistical methodology, have been applied, for example, in the growth of cancer cells by Ferrante et al. [9] and by Albano and Giorno [1],

using homogeneous and non homogeneous Gompertz processes respectively. They have been applied in the field of energy consumption by Skiadas et al. [20] and by Giovanis et al. [10] in the case of electrical consumption in Greece and the USA, using logistic and Bass diffusion processes, respectively. Gutiérrez et al. [11] applied a Gompertz model to the modelling of natural gas consumption in Spain, and Gutiérrez et al. [12] used one to study electricity consumption in Morocco. In environmental sciences, diffusion processes have been used by Gutiérrez et al. [13] to model CO₂ emissions in Spain (using a diffusion process with cubic drift) and by Gutiérrez et al. [14] with respect to the emissions of greenhouse gases attributable to the activities of land transport (using an inverse CIR diffusion process).

In the present study, we examine a new type of stochastic gamma diffusion process (SGDP), based on the methods of growth function formulation (see Skiadas [19]). The SGDP presented is obtained by adding white noise fluctuations to the ordinary differential equation characterizing the density function of a Gamma distribution. The paper is organized as follows: in the next section, we introduce the model from the point of view of the Kolmogorov equation as the stochastic differential equation. From this initial approach, we obtain the transition probability density function (TPDF) and the moments of the process. In Section 3, we study the statistical inference on the model. Based on discrete sampling, we obtain the likelihood estimators of the parameters, their distribution and corresponding confidence interval. In Section 4, we study an application based on simulated data.

§2. The SGDP and its characteristics

2.1. The model

The SGDP can be defined as a one-dimensional diffusion process $\{x(t), t \in [t_1, T], t_1 > 0\}$ on $(0, \infty)$ with infinitesimal moments (drift parameter and diffusion coefficients) given by

$$\begin{aligned} a(x, t) &= \left(\frac{\alpha}{t} - \beta\right) x \\ b(x, t) &= \sigma^2 x^2 \end{aligned} \quad (1)$$

where α , β and σ are time-independent real parameters and to be estimated.

The TPDF of the process is denoted by $f(y, t | x, s)$, and then f is the unique solution to the following equations, known as the forward Fokker Planck and the backward Kolmogorov equations:

$$\begin{aligned} \frac{\partial f(y, t | x, s)}{\partial t} &= -\frac{\partial}{\partial x} [a(y, t) f(y, t | x, s)] + \frac{1}{2} \frac{\partial^2}{\partial x^2} [b(y, t) f(y, t | x, s)] \\ \frac{\partial f(y, t | x, s)}{\partial s} &= -a(x, t) \frac{\partial f(y, t | x, s)}{\partial x} - \frac{1}{2} b(x, t) \frac{\partial^2 f(y, t | x, s)}{\partial x^2} \end{aligned}$$

with the delta type initial condition $\lim_{t \rightarrow s} f(y, t | x, s) = \delta(y - x)$

Remark 1. Alternatively, the above-defined process can be considered as the solution to Itô's

stochastic differential equation (SDE)

$$dx(t) = \left(\frac{\alpha}{t} - \beta\right)x(t)dt + \sigma x(t)dw(t) \tag{2}$$

with the initial condition $P[x(t_1) = x_{t_1}] = 1$, x_{t_1} is positive real, and where $w(t)$ is a one-dimensional standard Wiener process.

Note that in the absence of white noise (i.e $\sigma = 0$), the solution of the ordinary differential equation associated with the SDE Eq. (2) is $x(t) = kt^\alpha e^{-\beta t}$, which is proportional to the Gamma density function.

Remark 2. For $\alpha = 0$ and $\beta < 0$, we find the stochastic homogeneous lognormal diffusion process studied by Tintner et al. [22].

2.2. The TPDF and the moments

The standard solution to the above equations can be obtained using Ricciardi's theorem (see Ricciardi [17]) for the transformation of the diffusion process into the Wiener process. The infinitesimal moments Eq.(1) verify the conditions of the cited theorem ; therefore such a transform exists and has the following form:

$$\begin{aligned} \phi(t) &= t \\ \psi(x, t) &= \frac{1}{\sigma} \log(x) - \frac{1}{\sigma} \left[\alpha \log(t) - \left(\beta + \frac{\sigma^2}{2}\right)t \right]. \end{aligned}$$

From the above, the TPDF for the considered process is

$$f(y, t | x, s) = [2\pi\sigma^2(t-s)]^{-1/2} \exp\left(-\frac{[\log(y) - \mu(s, t, x)]^2}{2\sigma^2(t-s)}\right) \tag{3}$$

where $\mu(s, t, x)$ is given by

$$\mu(s, t, x) = \log(x) + \alpha \log(t/s) - (\beta + \sigma^2/2)(t-s).$$

This TPDF is the density of the one-dimensional lognormal distribution: $\Lambda_1[\mu(s, t, x), \sigma^2(t-s)]$.

Taking into account that with the initial condition $P(x(t_1) = x_1) = 1$, the random variable $x(t)$ is distributed as $\Lambda_1[\mu(t_1, t, x_{t_1}), \sigma^2(t-t_1)]$ and bearing in mind the properties of this distribution, the r th moment (r is a non negative integer) of the process is expressed by

$$\begin{aligned} \mathbb{E}(x^r(t)) &= \exp\left(r\mu(s, t, x_{t_1}) + \frac{r^2\sigma^2}{2}(t-t_1)\right) \\ &= x_{t_1}^r \left(\frac{t}{t_1}\right)^{r\alpha} e^{-r\beta(t-t_1)} \exp\left\{\frac{r(r-1)}{2}\sigma^2(t-t_1)\right\}. \end{aligned}$$

From which, the trend function of the process is

$$\mathbb{E}(x(t)) = \frac{x_{t_1} e^{\beta t_1}}{t_1^\alpha} t^\alpha e^{-\beta t} \tag{4}$$

and the variance function is

$$\text{Var}(x(t)) = x_1^2 \left(\frac{t}{t_1}\right)^{2\alpha} e^{-2\beta(t-t_1)} \left(e^{\sigma^2(t-t_1)} - 1\right).$$

Note also that the trend function Eq.(4) is proportional to the density function of the Gamma distribution.

§3. Statistical inference on the model

3.1. Parameter likelihood estimation

Let us consider a discrete sampling of the process, that is, for fixed times t_1, t_2, \dots, t_n we observe the variables $x(t_1), \dots, x(t_n)$ whose values x_1, \dots, x_n make up the basic sample from which the inferential process is carried out. From Eq.(2), and assuming the initial condition $P[x(t_1) = x_1] = 1$, the likelihood function for the sample can be expressed as:

$$\mathbb{L}(x_1, \dots, x_n, \alpha, \beta, \sigma^2) = \prod_{i=2}^n f(x_i, t_i | x_{i-1}, t_{i-1}).$$

Now we transform the observed values x_1, \dots, x_n as follows:

$$v_i = (t_i - t_{i-1})^{-1/2} (\log(x_i) - \log(x_{i-1})), \quad i = 2, \dots, n.$$

Then, the likelihood function for the transformed sample is

$$\mathbb{L}(v_2, \dots, v_n, \mathbf{a}, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{\frac{n-1}{2}}} \exp\left(-\frac{1}{2\sigma^2}(\mathbf{V} - \mathbf{U}'\mathbf{a})'(\mathbf{V} - \mathbf{U}'\mathbf{a})\right) \tag{5}$$

where $\mathbf{V} = (v_2, \dots, v_n)'$, $\mathbf{a} = (\alpha, -(\beta + \sigma^2/2))'$ and \mathbf{U} is the $2 \times (n - 1)$ matrix, whose rank is assumed to be 2, and is given by: $\mathbf{U} = (\mathbf{u}_2, \dots, \mathbf{u}_n)$, and where, for $i = 2, \dots, n$, $\mathbf{u}_i = (t_i - t_{i-1})^{-1/2} (\log(t_i/t_{i-1}), t_i - t_{i-1})'$.

After calculating the derivatives of the log-likelihood function with respect to \mathbf{a} and σ^2 , the likelihood equation is

$$\begin{aligned} \mathbf{U}(\mathbf{V} - \mathbf{U}'\hat{\mathbf{a}}) &= 0 \\ (n - 1)\hat{\sigma}^2 &= (\mathbf{V} - \mathbf{U}'\hat{\mathbf{a}})'(\mathbf{V} - \mathbf{U}'\hat{\mathbf{a}}). \end{aligned}$$

After various algebraic operations (omitted here), the maximum likelihood estimators (MLEs) of the parameters are found to be:

$$\hat{\mathbf{a}} = (\mathbf{U}\mathbf{U}')^{-1}\mathbf{U}\mathbf{V} \tag{6}$$

$$(n - 1)\hat{\sigma}^2 = \mathbf{V}'\mathbf{H}_\mathbf{U}\mathbf{V} \tag{7}$$

where $\mathbf{H}_\mathbf{U} = \mathbf{I}_{n-1}\mathbf{U}'(\mathbf{U}\mathbf{U}')^{-1}\mathbf{U}$ is a symmetric and idempotent matrix.

3.2. Properties of likelihood estimators

3.2.1. Distributions of MLEs

Eq.(5) is also the density function of the random vector \mathbf{V} , and can be rewritten as

$$L(\mathbf{V}, \mathbf{a}, \sigma^2) = \frac{1}{(2\pi)^{(n-1)/2} |\sigma^2 \mathbf{I}_{n-1}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{V} - \mathbf{U}'\mathbf{a})' (\sigma^2 \mathbf{I}_{n-1})^{-1} (\mathbf{V} - \mathbf{U}'\mathbf{a})\right)$$

from which, we deduce that

$$\mathbf{V} \sim \mathcal{N}_{n-1} [\mathbf{U}'\mathbf{a}, \sigma^2 \mathbf{I}_{n-1}].$$

The rank of the matrix \mathbf{U} is assumed to be 2. Then the matrix $(\mathbf{U}\mathbf{U}')^{-1}\mathbf{U}$ has the same rank, and therefore

$$(\mathbf{U}\mathbf{U}')^{-1}\mathbf{U}\mathbf{V} \sim \mathcal{N}_2 [(\mathbf{U}\mathbf{U}')^{-1}\mathbf{U}\mathbf{U}'\mathbf{a}, \sigma^2(\mathbf{U}\mathbf{U}')^{-1}(\mathbf{U}\mathbf{U}')\mathbf{U}\mathbf{U}'^{-1}]$$

and finally, we have

$$\hat{\mathbf{a}} \sim \mathcal{N}_2 [\mathbf{a}, \sigma^2(\mathbf{U}\mathbf{U}')^{-1}].$$

Using a known results in multivariate analysis (see for example [18]) we have:

$$\frac{\mathbf{V}' \mathbf{H}_U \mathbf{V}}{\sigma} \frac{\mathbf{V}}{\sigma} = \frac{(n-1)\hat{\sigma}^2}{\sigma^2} \sim \chi^2_{(n-3)}$$

and $\hat{\mathbf{a}}$ and $\hat{\sigma}^2$ are independently distributed.

3.2.2. Sufficiency and Completeness

By subtracting, and adding $\mathbf{U}'\hat{\mathbf{a}}$ to $\mathbf{V} - \mathbf{U}'\mathbf{a}$, the expression Eq.(5) becomes

$$L_{v_2, \dots, v_n}(\mathbf{a}, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{\frac{n-1}{2}}} \exp\left(-\frac{1}{2\sigma^2} [(n-1)\hat{\sigma}^2 + (\hat{\mathbf{a}} - \mathbf{a})'\mathbf{U}\mathbf{U}'(\hat{\mathbf{a}} - \mathbf{a})]\right)$$

which means that $(\hat{\mathbf{a}}, \hat{\sigma}^2)$ is conjointly sufficient for (\mathbf{a}, σ^2) .

The completeness follows by means of reasoning similar to that established for the maximum likelihood estimators of the parameters of the multivariate normal distribution (see, for example, Anderson [3]).

As the estimators $\hat{\mathbf{a}}$ and $\frac{(n-1)\hat{\sigma}^2}{(n-3)\sigma^2}$ are sufficient for \mathbf{a} and σ^2 respectively, then we can deduce that they are the UMVUE.

3.3. Parameter confidence intervals

The $\gamma\%$ confidence interval for the parameter σ^2 is given, by

$$\left(\frac{(n-1)\hat{\sigma}^2}{\chi^2_{n-3, \frac{\gamma}{2}}}, \frac{(n-1)\hat{\sigma}^2}{\chi^2_{n-3, 1-\frac{\gamma}{2}}} \right) \tag{8}$$

and the $\gamma\%$ confidence interval for the parameter α is given, by

$$P \left(\alpha \in \left[\hat{\alpha} \pm \hat{\sigma} \left(\frac{n-1}{n-3} A_{11} F_{1,n-3,\gamma} \right)^{1/2} \right] \right) = 1 - \gamma \tag{9}$$

where $\chi_{n,\gamma}^2$ and $F_{m,n,\gamma}$ are the upper 100γ per cent points of the χ^2 with n degrees of freedom and the F -distribution with m and n degrees of freedom, respectively, and A_{11} is the first elements of the principal diagonal of the matrix $(\mathbf{UU}')^{-1}$ and where \mathbf{UU}' is

$$\mathbf{UU}' = \begin{pmatrix} \sum_{i=2}^n \log^2(t_i/t_{i-1}) & \log(t_n/t_1) \\ \log(t_n/t_1) & n-1 \end{pmatrix}.$$

§4. Simulation

The trajectory of the model can be obtained by simulating the exact solution of SDE Eq.(2). This solution can be obtained by means of Itô's formula applied to the transform $\log(x(t))$, from which we obtain the following SDE

$$d[\log(x(t))] = [\alpha - (\beta + \sigma^2/2)]dt + \sigma dw(t).$$

By integrating and simplifying, the solution of the SDE Eq.(2) is given as

$$x(t) = x_{t_1} \left(\frac{t}{t_1} \right)^\alpha e^{-(\beta + \sigma^2/2)(t-t_1)} \exp[\sigma(w(t) - w(t_1))].$$

From this explicit solution, the simulated trajectories of the process are obtained from the following discretizing time interval $[t_1, T]$: $t_i = t_1 + (i - 1)h$, for $i = 1, \dots, N$ (N is an integer and h is the discretization step), taking into account that the random variable in the latter expression $\sigma(w(t) - w(t_1))$ is distributed as a one-dimensional normal distribution $\mathcal{N}_1(0, \sigma^2(t - t_1))$.

In this simulation, we consider M process trajectories, each of which has N observations, estimating the parameters by means of equations Eq.(6) and Eq.(7). In total M estimators are obtained for each parameter (i.e. one vector of M components), from which we compute the sample mean and the standard error (SE) of each estimator.

Let us now study the evolution of the mean and the standard error of the estimators with respect to the variation in the number N and h . The results of this study are shown in Table 1.

A MatLab program was implemented to carry out the calculation required for this study. The true parameter values considered in this simulation are $\alpha = 2, \beta = 0.5, \sigma = 0.1$ and the start point is $x_{t_1} = 2$, and $t_1 = 0.5$.

Figure (Fig.1) shows some simulated trajectories of the process and the estimated trend function (ETF) of the process obtained using the Zehna theorem, replacing the parameters

Table 1: Mean and standard error of the estimators

h	num.obs.	mean($\hat{\alpha}$)	SE($\hat{\alpha}$)	mean($\hat{\beta}$)	SE($\hat{\beta}$)	mean($\hat{\sigma}$)	SE($\hat{\sigma}$)
0.05	100	2.0071	0.2279	0.4983	0.0921	0.0991	0.0071
0.05	500	2.0059	0.1336	0.5003	0.0273	0.0998	0.0029
0.05	1000	1.9893	0.1259	0.4984	0.0176	0.0998	0.0023
0.1	100	1.9981	0.1797	0.5012	0.0543	0.0986	0.0072
0.1	500	1.9957	0.1220	0.4996	0.0171	0.0999	0.0033
0.1	1000	1.9989	0.1177	0.5005	0.0111	0.0997	0.0022
0.5	100	2.0016	0.1250	0.4995	0.0182	0.0983	0.0069
0.5	500	1.9944	0.1059	0.5001	0.0066	0.0996	0.0032
0.5	1000	1.9938	0.1097	0.5002	0.0043	0.0997	0.0023
1	100	2.0018	0.1171	0.5008	0.0118	0.0989	0.0071
1	500	2.0083	0.1010	0.5004	0.0046	0.0996	0.0032
1	1000	2.0027	0.1049	0.5002	0.0033	0.0999	0.0023

by their estimators in Eq.(4). In this figure (Fig.1 the dark line represents the ETF. In this simulation we assume $h = 0.1$, $N = 100$ and $M = 20$.

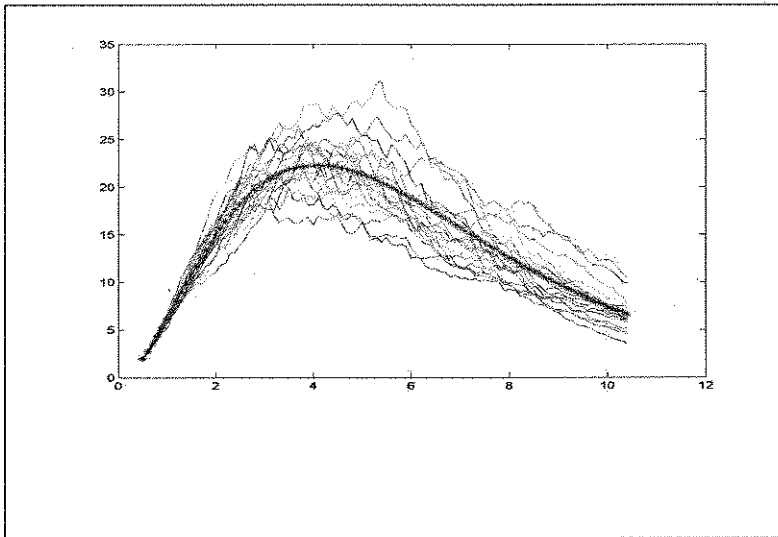


Figure 1: Simulated trajectories of the SGDP versus to ETF

Acknowledgements

This work was supported partially by research project MTM 2005-09209, Ministerio de Educación y Ciencia, and project P06-FQM-02271, Junta de Andalucía, Spain.

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